Modeling Forest Biomass Using LiDAR Remote Sensing on an Urban Landscape Shannon MacDonald¹, Dr. Danijela Puric-Mladenovic², & Joshua Shea³

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Background

The urban forest provides numerous ecological goods and services and as such is becoming increasingly recognized as a critical component of the urban landscape. Urban natural areas, often being remnants of native vegetation, are also the most cost effective and long-term sustainable component of urban forests. Their structure, measured and mapped as live tree biomass, is an expression of the ecosystem services and ecological functions they provide. Biomass mapping can be improved by incorporating Light Detection and Ranging (LiDAR) data in model development and extrapolation. While research and operational application of using LiDAR to inventory the structure of managed forests has grown over 25 years, application of these methods has not been well studied in urban areas.

Study Area

The City of Kitchener (Figure 1) is one of the first municipalities in Ontario with enough field data to establish a comprehensive baseline condition of its natural cover, with 549 permanent sampling plots.

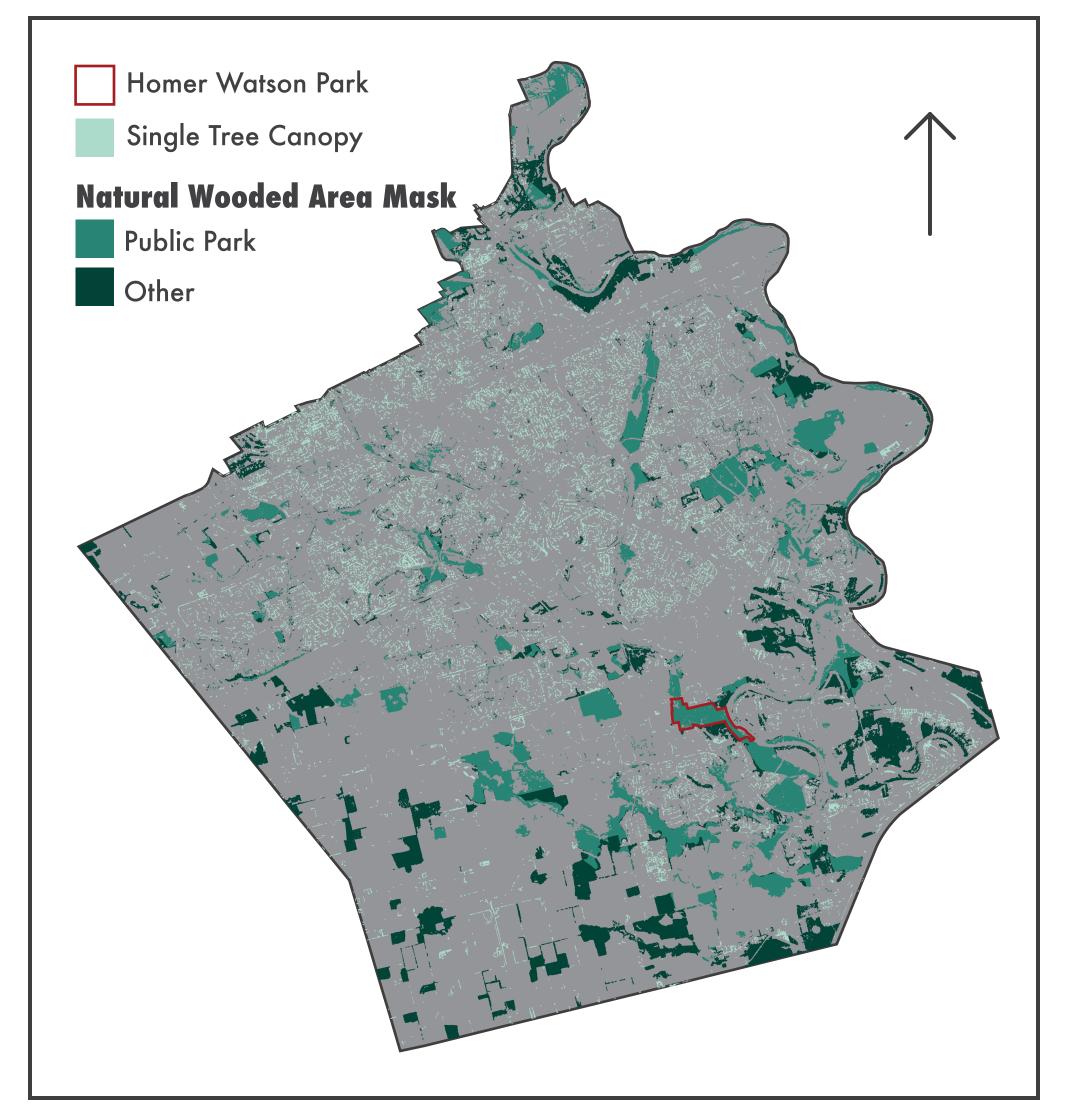
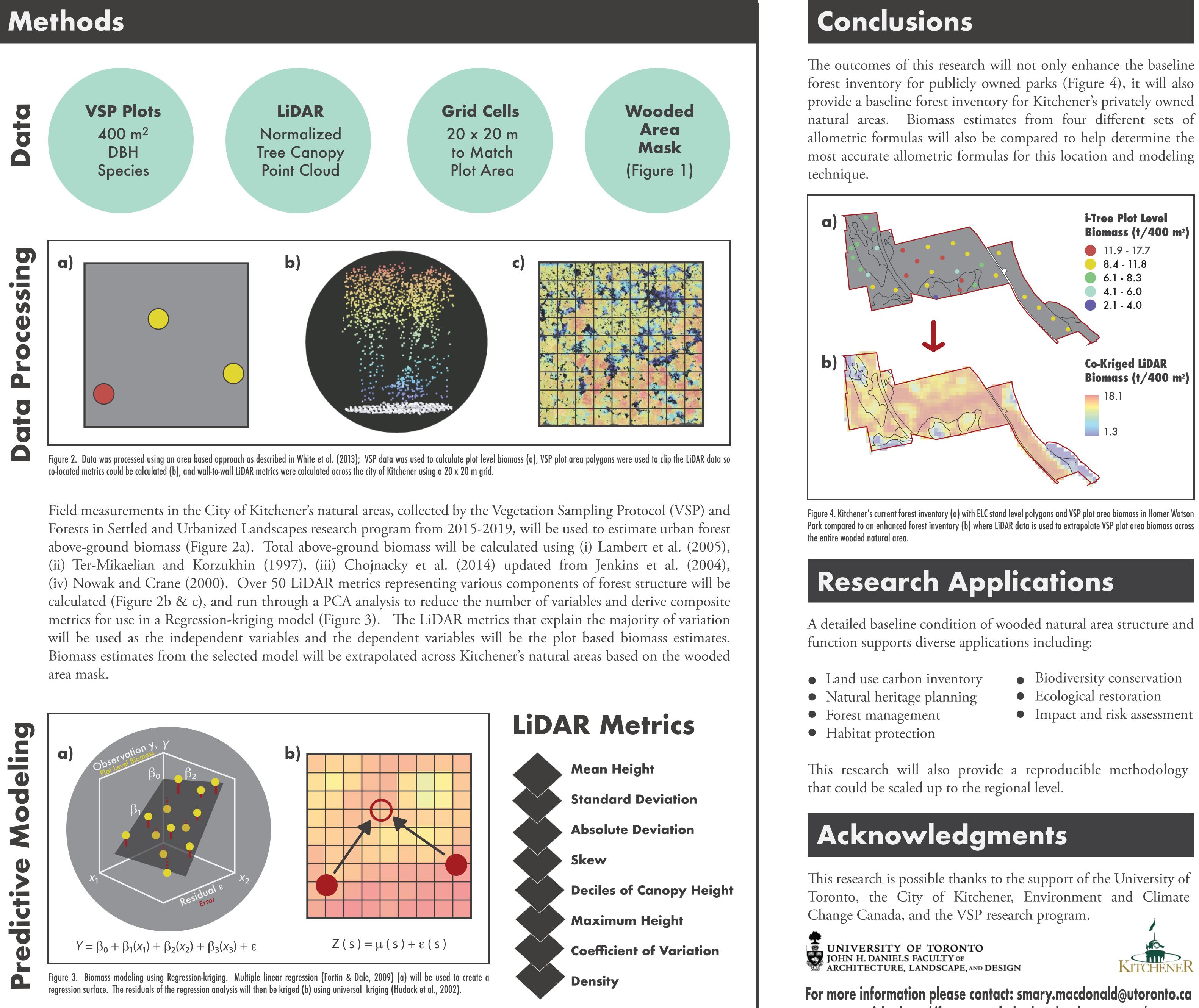
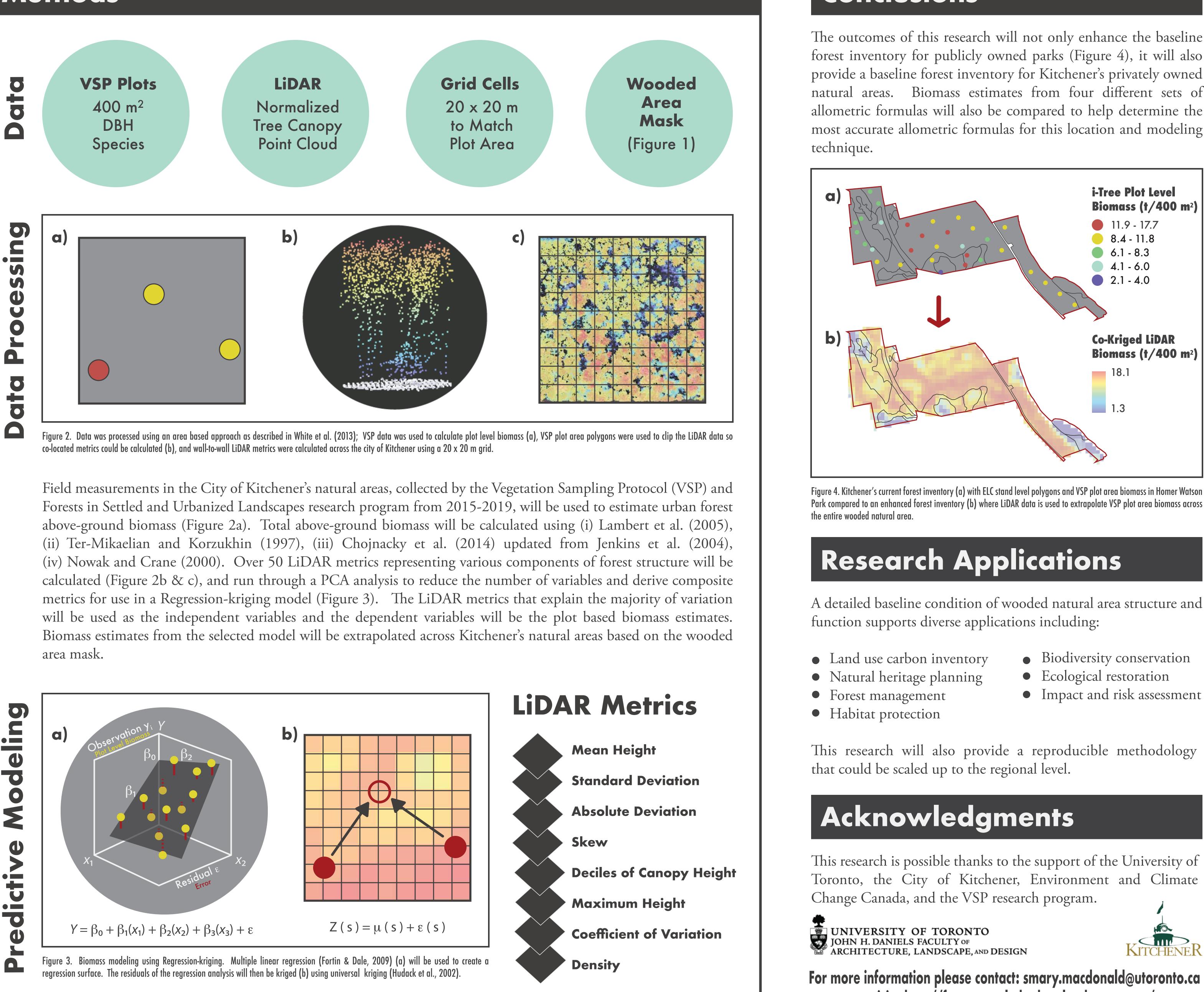


Figure 1. Study area map of the City of Kitchener's Urban Tree Canopy (UTC), based on a LiDAR derived canopy model. Natural Wooded Area Mask contains UTC that overlays Kitchener's Park and SOLRIS wooded area polygons.

Objective

While biomass averages can be readily derived and extrapolated from plot data, our objective is the improvement of biomass estimates and mapping them across natural wooded areas by utilizing LiDAR and an area-based regression-kriging model.





or visit: http://forests-settled-urban-landscapes.org/